# Product Data

### 6-Ch. A&V Recording Module — Type 3030

Part of Intelligent Data Acquisition System Type 3561

#### USES:

- O Input module for multichannel acoustic and vibration measurements
- O In multichannel applications such as STSF, modal analysis, ODS, etc.

#### FEATURES:

- O Input via 37-pole D-sub connector designed for use with up to:
  - 6 × Microphone Type 4196
  - 6  $\times$  Preamplifier Type 2669 with prepolarized  $^{1/2''}$  microphone
  - $-6 \times \overline{\text{DeltaTron}^{\&}}$  Accelerometer (CCLD) or any combination

## O Supports transducers with remote ID via $\mu LAN$ interface

- O Charge Injection Calibration facility
- O Cable fault detection via downloaded software
- O Overload detection for out-of-band frequencies
- O DC, 0.7 Hz and 22.4 Hz high-pass filters, independently set for each channel
- O Independent input ranges for each channel, with autorange
- O Long, real-time, time records: 512 k or 2048 k samples total for the enabled number of channels
- O Powerful built-in digital signal processor (prepared for DSP expansion board)
- O Automatic DC-offset compensation

6-Ch. A & V Recording Module Type 3030 is an acoustic and vibration input module which meets the requirements for multichannel measurements with Intelligent Data Acquisition System (IDA) Type 3561.

The input module uses a single, 37pin D-sub connector for connecting six transducers at a time. This allows simple cabling for large systems comprising many transducers, as used, for example, for the measurement of spatial transformation of sound fields, modal analysis or operational deflection shapes. A tri-colour LED indicates the status of the module (overload, recording, downloaded DSP code).

Downloaded DSP software defines the functions available with the module, for example, decimation and zoom for recording time histories.

#### Transducers

A cable which branches to six 3-pole LEMO connectors allows you to connect an array of six microphones Type 4196 to the input. A pistonphone adaptor is also available, allowing simultaneous calibration of the six channels. Other prepolarized microphones, including those employing DeltaTron<sup>®</sup> Preamplifier Type 2671, can also be used, as can Delta-Tron<sup>®</sup> Accelerometers. These, however, require special cabling and/or adaptors.

#### **Cable Fault Detection**

Type 3030 employs two methods of detecting cable breaks.

For microphones, the supply current to the microphones is monitored on-line and in real time. If the current exceeds the upper or lower limit of the allowed band, an error event is generated.

For DeltaTron<sup>®</sup> accelerometers or microphones using DeltaTron<sup>®</sup> preamplifiers, the supply voltage can be monitored off-line. If the acceptable limits are exceeded, an error event is generated and you can stop the measurement and measure the working voltage to help determine the cause of the error.

#### **Independent Channels**

The channels of the input module can be set up independently. This means that you can set up the high-pass filters and input gain separately and,



if required, attach different types of transducer to different channels.

#### **Remote ID**

Type 3030 is prepared for use with transducers with remote ID – serial number, sensitivity, etc.

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### **Specifications 3030**

UPPER FREQUENCY: 1 kHz to 12.8 kHz: 30 dB 12.8 kHz at f<sub>s</sub> =32.768 kHz 25.6 kHz at f<sub>s</sub>=65.536 kHz SAMPLING: 32768 Hz (inputs and CIC output) & 65536 Hz (inputs only) A/D Conversion: 16 bit Input Coupling: 22.4 Hz high-pass filter @-0.1 dB, slope +0.1 dB  $-18 \, \text{dB/oct} \, (f_{\text{L}} = 22.4 \, \text{Hz})$ 0.7 Hz high-pass filter @ -0.1 dB, slope  $-6 \text{ dB/oct} (f_L = 0.7 \text{ Hz})$ DC-Direct (f\_L = 0 Hz) Analog Special Functions: CCLD on/off Charge Injection Calibration: Max. V<sub>out</sub>: 5V<sub>rms</sub> Frequency Range: DC to 12.8 kHz Analog Self-test (prepared) Digital DC-offset Adjustment Cable Fault Detection: +15 V transducer supply current monitoring Fault Detection Current Adjustment: Dual current detector 0 to 10 mA, 8-bit resolution Remote ID between Transducer and Frontend: 223 6 mV Communication via uLAN interface 707.1 mV Automatic Input Type Select: Prepared 2.236 V Working Voltage Meas. for CCLD: 35 V<sub>peak</sub>, ±0.5 V 7 071 V **INPUT VOLTAGE:** 7 ranges from 7.071 mV\_{peak} to 7.07 V\_{peak} in 10 dB steps INPUT IMPEDANCE: Direct, microphone: 1 MΩ || <200 pF **CCLD:** > 100kΩ || <200 pF MAXIMUM INPUT VOLTAGE: 50 V, 35 V<sub>rms</sub> MAXIMUM INDUCED COMMON MODE VOLTAGE: range): 1 V<sub>peak</sub> SUPPLY FOR CCLD ACCELEROMETERS: 4 mA from +28 V source COMMON-MODE REJECTION: DC: 50 dB 0 to 1 kHz: 40 dB

#### CROSSTALK (SOURCE: 50 Ω): Between any two channels of module or between any two channels in different modules: 0 to 2 kHz: -100 dB 2 kHz to 12.8 kHz: -85 dB ATTENUATOR LINEARITY: ANTIALIASING FILTER (fs = 32768 Hz & fs = 65536 Hz): Provides at least 80 dB attenuation of those inputs frequencies which can cause aliasing Passband: DC to 25.6 kHz @ -0.1 dB, slope -18 dB/oct

OVERLOAD DETECTION: Applied before filters

TOTAL HARMONIC DISTORTION: At least 80 dB below max. input (≈0.01%)

#### NOISE (Linear 10 to 25.6 kHz):

Input Range Equivalent Input Noise 7.071 mV  $3 \mu V_{rms}$ 22.36 mV  $3 \mu V_{rms}$  $5\,\mu V_{rms}$ 70.71 mV  $10 \mu V_{rms}$  $31 \mu V_{rms}$ 

#### **OVERALL FREQUENCY RESPONSE:** $f_L$ to $f_U$ : ±0.1 dB

 $100\,\mu V_{rms}$ 

 $316 \mu V_{rms}$ 

AMPLITUDE LINEARITY:

0 to 40 dB below full scale: ±0.1 dB 40 to 60 dB below full scale: ±0.4 dB 60 to 80 dB below full scale: +2.0 dB

ABSOLUTE AMPLITUDE PRECISION: ±0.1 dB, 2.236 V input range (1.024 kHz)

CHANNEL-TO-CHANNEL MATCH (any input

Maximum Gain Difference: 0.2 dB from lower frequency limit,  $f_{\text{L}},$  to upper frequency limit,  $f_{\text{U}}$ Maximum Phase Difference (within one frame):  $1.1^{\circ}-0.1^{\circ}\times(f$  /f\_) from f\_ to  $10\times f_L;$  $0.1^\circ$  from 10  $\times$   $f_L$  to 640 Hz;  $1.0^{\circ} \times$  (f/640) from 640 Hz to 6.4 kHz

CHANNEL-TO-CHANNEL MATCH (same input range):

Maximum Gain Difference: 0.2 dB from lower frequency limit, f<sub>1</sub>, to upper frequency limit, fu Maximum Phase Difference (within one frame):

 $1.1^{\circ} - 0.1^{\circ} \times (f / f_L)$  from  $f_L$  to  $10 \times f_L$ ;  $0.1^{\circ}$  from  $10 \times f_L$  to 1280 Hz;  $1.0^{\circ} \times (f/1280)$  from 1280 Hz to 12.8 kHz

#### **Digital Signal Processing:**

The functionality of Type 3030 is dependent on the DSP software downloaded from the application software used

PROCESSOR Motorola DSP56002 @ 60 MHz

#### **Power Supply:**

Power Supply Module Type 2823

#### POWER CONSUMPTION:

Approx. 13W (max. value)

Voltage (V)	Typical (mA)	Max. (mA)
-15	110	220
+ 5	450	
+ 8	150	160
+15	110	220
+28	30	

#### **Dimensions:**

Type 3561 module dimensions Height: 134.0 mm (5.28 in) Length: 42.5 mm (1.67 in) Width: 230 mm (9.06 in) Weight: 1.1 kg (2.4 lb.)

#### **Compliance with Standards:**



When incorporated into Intelligent Data Acquisition System Type 3561 Type 3030 complies with the system standards stated in the Product Data for Type 3561 (BP 1447)

### Ordering Information

#### **Optional Accessories**

Type 4196: AO 0432:	Prepolarized Microphone 10 m 37-pole D-sub to $6 \times 3$ -pole
	LEMO cable for use with Microphone Type 4196
AO 0432/x:	As AO 0432 but xm long

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